### Extensive Games and the Sequence Form

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- Linear programming and zero-sum games
- Extensive games
	- perfect recall and the sequence form
	- computing equilibria with the sequence form

Linear programming duality

Primal LP:

**maximize** *c* ⊤*y*

subject to  $Ay \leq b$ ,

 $y > 0$ .

Dual LP:

**minimize** *x* ⊤*b* subject to  $x \geq 0$ , *x* '*A* ≥ *c* '.

Primal LP: **maximize** *c* ⊤*y* subject to  $Ay < b$ ,  $y > 0$ . Dual LP: **minimize** *x* ⊤*b* subject to  $x > 0$ , *x* '*A* ≥ *c* '.

**Weak LP duality:** For any **feasible** primal *y*, dual *x* :

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$$
(\boldsymbol{c}^\top)\boldsymbol{y} \leq (\boldsymbol{x}^\top\boldsymbol{A})\boldsymbol{y} = \boldsymbol{x}^\top(\boldsymbol{A}\boldsymbol{y}) \leq \boldsymbol{x}^\top(\boldsymbol{b})
$$

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So *c* ⊤*y* = *x* <sup>⊤</sup>*b* ⇒ *y* optimal for primal LP, *x* optimal for dual LP.

Primal LP:

#### Dual LP:

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**Strong LP duality:** If both primal and dual LP are feasible, then they have (optimal) solutions *y* and *x* with *c* ⊤*y* = *x* ⊤*b*.

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### **Tucker diagram**

 $\text{Primal LP: } \textbf{maximize } \textbf{c} \cdot \textbf{y} \text{ subject to } \textbf{A} \textbf{y} \leq \textbf{b}, \textbf{y} \geq \textbf{0}.$ Dual LP: **minimize**  $x'$  *b* subject to  $x'$  *A*  $\geq$  *c*<sup> $\perp$ </sup>,  $x \geq 0$ .



# **Zero-sum game** (*A*, −*A*) **written as general LP**

Minimizer: **minimize** *u* subject to  $Ay \leq 1$ *u*,  $y \in Y$ . Maximizer: **maximize** *v* subject to *x* <sup>⊤</sup>*A* ≥ *v***1** <sup>⊤</sup>, *x* ∈ *X*.



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# **Simpler LP with positive payoffs**

*x*<sup>-</sup>(*A* + 1α1<sup>-</sup>)*y* = *x*<sup>-</sup>*Ay* + *x*<sup>-1</sup>α1<sup></sup><sup>*y*</sup> = *x*<sup>-</sup>*Ay* + α

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*x*<sup>-</sup>(*A* + 1α1<sup>-</sup>)*y* = *x*<sup>-</sup>*Ay* + *x*<sup>-1</sup>α1<sup></sup><sup>*y*</sup> = *x*<sup>-</sup>*Ay* + α  $\Rightarrow$  w.l.o.g.  $A > 0$ , min-max cost  $u > 0$ , max-min payoff  $v > 0$ , replace **y** by  $y' = y\frac{1}{y}$  $\frac{1}{u}$ , and **x** by  $x' = x \frac{1}{v}$ *v* , Minimizer: **maximize 1**<sup>⊤</sup>**y'** (=  $\frac{1}{u}$ ) subject to **Ay'** ≤ **1**, Maximizer: **minimize**  $\mathbf{1}^\top \mathbf{x}'$  (=  $\frac{1}{\mathbf{v}}$ ) subject to  $\mathbf{x}'^\top \mathbf{A} \geq \mathbf{1}^\top$ **1 1** · ··· <u>1</u> ∨ *A y* ′ ≥ **0**  $x' \ge 0$   $\vert$   $A$   $\vert \le$ **1 1** . . . **1** →max  $\hookrightarrow$  min

# Extensive Games,

# Sequence Form

### **Game tree (game in extensive form)**



# **Strategic (or normal) form**

**Strategy** of a player:

specifies a move for **every** information set of that player.



# **Reduced strategic form**

**Reduced strategy** of a player:

specifies a move for every information set of that player, **except** for those information sets unreachable due to an **own** earlier move (where we write ∗ instead of a move).



# **Exponential blowup of strategic form**

number of pure strategies typically **exponential** in number of information sets.



number of information sets number of pure strategies  $= 2^{\ell}$ 

 $L_1$   $\setminus$   $R_1$   $L_2$   $\setminus$   $R_2$   $L_3$   $\setminus$   $R_3$   $L_2$   $\setminus$   $R_\ell$ 

 $\mathbb{Z}$ 

*c*ℓ

**Example** [Kuhn]: simplified poker game,

number of information sets  $=$  13 number of pure strategies  $= 8192$ 

# **Exponential blowup of reduced strategic form**

**Example**: Game with (1) **bounded** number of moves per node, (2) no **subgames** (otherwise simplify by solving subgames first).



This tree with *n* nodes:  $\approx 2^{\sqrt{n}/2}$  strategies per player, reduced strategic form still (sub-)**exponential** in **tree** size.

# **Use behavior strategies**

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Mixed strategy too redundant, use behavior strategy instead:

- only one variable per **move**: player 1 chooses *L* with probability *X<sup>L</sup>* player 1 chooses *R* with probability *X<sup>R</sup>* . . . player 2 chooses *a* with probability *Y<sup>a</sup>* . . .
- expected payoff  $=$

 $5 Y_a X_l + 10 Y_a X_R Y_p X_{ll} + 15 Y_a X_R Y_p X_{l} + \cdots$ 

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- expected payoff  $=$  $5 Y_a X_i + 10 Y_a X_R Y_n X_{ii} + 15 Y_a X_R Y_n X_{i'} + \cdots$
- problem: **nonlinear**!

# **Variable transformation**

For each **sequence**  $\sigma$  of moves of player 1 introduce new variable **x**<sub>σ</sub>

• new variables replace products:

if  $σ = PQRS$  then  $x<sub>σ</sub> = X<sub>P</sub>X<sub>Q</sub>X<sub>R</sub>X<sub>S</sub>$ 

• Example:

 $x_l = X_l$  $X_{RU} = X_R X_{U}$ . . . *y<sup>a</sup>* = *Y<sup>a</sup>*  $y_{ab} = Y_a Y_b$ . . .

• expected payoff =  $5 x_L y_a + 10 x_R y_b + 15 x_R y_b + \cdots$ is **linear** in variables of one player.

# **New paradigm: Sequences instead of pure strategies**

#### **Before:**



#### **After:**





# **Realization plans**

**Realization plan**  $x = (x_0, x_L, x_R, x_C, x_D, x_{RU}, x_{RV})$ 

(= vector of realization probabilities) characterized by  $x > 0$  and **linear** equalities

$$
x_0 = 1
$$
  
\n
$$
x_0 = x_L + x_R
$$
  
\n
$$
x_0 = x_L + x_R
$$
  
\n
$$
x_R = x_C + x_D
$$
  
\n
$$
x_{RU} + x_{RV}
$$

written as  $E x = e$  with

$$
E = \begin{bmatrix} 1 \\ -1 & 1 & 1 \\ -1 & & 1 & 1 \\ & & -1 & & 1 & 1 \end{bmatrix}, \qquad e = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}
$$

# **The sequence form**

Payoff matrix *A*



expected payoff *x* ⊤*Ay*,

columns played with **y** subject to  $y > 0$ ,  $F y = f$ .

rows played with **x** subject to  $x > 0$ ,  $Ex = e$ ,

# **How to play**

.

**Given:** realization plan **x** with  $E x = e$ .

Move *L* is last move of **unique** sequence, say  $PQL$ , where  $x_{PQL} + x_{PQR} = x_{PQ}$ .

$$
\Rightarrow \quad \text{behavior-probability}(L) = \frac{x_{PQL}}{x_{PQ}}
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Required assumption of **perfect recall** [Kuhn 1953, Selten 1975]: Each node in an information set is preceded by same sequence, here *PQ*, of the player's **own** earlier moves.



# Solving the Sequence Form:

# Constrained Games

# **Constrained games**

**Polyhedrally constrained game:**

Player 1's strategy set

 $X = \{x \in \mathbb{R}^m | Ex = e, x \ge 0\}$ 

e.g.  $E = [1 \ 1 \cdots 1], e = 1$ : strategy **simplex** 

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payoff matrices *A*, *B*, expected payoffs *x* ⊤*Ay*, *x* <sup>⊤</sup>*By* for (*x*, *y*) ∈ *X* × *Y*.

*x* in *X* best response against *y* in *Y*: solves primal LP

maximize *x* ⊤(*Ay*) subject to  $Ex = e$ *x* ≥ **0**

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Dual LP (with same value,  $=$  best response payoff to player 1):

minimize *e* ⊤*u* subject to *E* <sup>⊤</sup>*u* ≥ *Ay*

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*x*, *u* optimal ⇔ complementary slackness:

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\mathbf{x}^\top(\mathbf{E}^\top \mathbf{u} - \mathbf{A}\mathbf{y}) = \mathbf{0}
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$$
\mathbf{x}^\top(\mathbf{E}^\top \mathbf{u} - \mathbf{A} \mathbf{y}) = 0
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= best-response condition (only pure best responses can have positive probability)

#### **Constrained zero-sum games**

[Charnes 1953] Let *B* = −*A*. For  $v \in Y$ , best-response payoff to player  $1$  = value of LP maximize *x* ⊤(*Ay*) subject to  $E x = e$ *x* ≥ **0** equals value of dual LP minimize *e* ⊤*u* subject to *E* <sup>⊤</sup>*u* ≥ *Ay*

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# **Example**

**1)** Best-response LP max *x x* ⊤(*Ay*) subject to  $Ex = e$ *x* ≥ **0**

*x*∅ **1**−**1**−**1 0 2** *xL* **1 2** ≥ **0** *xR* **1** *xC* **1 1** *xD* **1 0**  $\overline{\phantom{a}}$ ↓ **1 0 0** max

**2) dual LP** min *u e* ⊤*u*

subject to *E* <sup>⊤</sup>*u* ≥ *Ay*



**1 0 0**  $\rightarrow$ min **2) dual LP**

min *u e* <sup>⊤</sup>*u* subject to *E* <sup>⊤</sup>*u* ≥ *Ay* *u***<sup>0</sup>** *u***<sup>1</sup>** *u***<sup>2</sup>**



**1 0 0**  $\rightarrow$ min

3) Treat 
$$
y
$$
 as a variable:

min  
\n*u, y*  
\nsubject to 
$$
E^{\top} u \ge Ay
$$
  
\n $Fy = f$   
\n $y \ge 0$ 



# **Linear size instead of exponential size**

**Input:** 2-player game tree with perfect recall.

**Theorem** [Romanovskii 1961], [von Stengel 1996] A zero-sum game is solved via an LP of linear size:

minimize 
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\mathbf{e}^{\top} \mathbf{u}
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subject to  $\mathbf{E}^{\top} \mathbf{u} - \mathbf{A} \mathbf{y} \ge \mathbf{0}$   
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[von Stengel / Elzen / Talman, *Econometrica* 2002] This algorithm mimicks the **Harsanyi-Selten tracing procedure** and finds a normal-form perfect equilibrium. (Allows variation of **starting vector** or **prior**.)

# **LCP – Lemke's algorithm**

Consider a **prior**  $(\bar{x}, \bar{v})$ , and a new variable  $z_0$  in the system



**Equilibrium condition**  $x^{\dagger} r = 0$ ,  $y^{\dagger} s = 0$ ,  $[z_0 = 0]$ .

Initial solution  $z_0 = 1$ ,  $x = 0$ ,  $y = 0$ .

#### **Complementary pivoting:**

 $x_{\sigma} \leftrightarrow r_{\sigma}$ ,  $y_{\tau} \leftrightarrow s_{\tau}$ , until  $z_{0}$  leaves the basis.