

Correlated Equilibria – Existence via LP Duality

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Plan

- Correlated equilibria of n -player games
- Existence proof without existence of Nash equilibria

Correlated equilibria

Nash equilibria

| | | | |
|---|--------|------|-------|
| | | II | |
| | | left | right |
| I | Top | 4, 4 | 5, 1 |
| | Bottom | 1, 5 | 0, 0 |

| | |
|------|---|
| play | |
| 0 | 0 |
| 1 | 0 |

| | |
|------|---|
| play | |
| 0 | 1 |
| 0 | 0 |

| | |
|------|-----|
| play | |
| 1/4 | 1/4 |
| 1/4 | 1/4 |

| |
|---|
| 1 |
| 5 |

| |
|---|
| 5 |
| 1 |

| |
|-----|
| 2.5 |
| 2.5 |

pay

pay

pay

Correlated equilibria

| | | | |
|---|--------|----------|----------|
| | | II | |
| | | left | right |
| I | Top | 4 5 | 4 1 |
| | Bottom | 1 0 | 5 0 |

| | |
|------|-----|
| play | |
| 0 | 1/2 |
| 1/2 | 0 |

| | |
|------|-----|
| play | |
| 1/3 | 1/3 |
| 1/3 | 0 |

| | |
|------|-----|
| play | |
| 0 | 1/3 |
| 1/3 | 1/3 |

| |
|---|
| 3 |
| 3 |

| |
|-------|
| 3 1/3 |
| 3 1/3 |

| |
|---|
| 2 |
| 2 |

pay

pay

pay

Incentive constraints

| | | | |
|---|--------|------|-------|
| | | II | |
| | | left | right |
| I | Top | 4 | 5 |
| | Bottom | 1 | 0 |
| | | 4 | 1 |
| | | 5 | 0 |

play

| | |
|---|---|
| a | b |
| c | d |

$$a + b + c + d = 1$$

$$a, b, c, d \geq 0$$

$$4a + 1b \geq 5a + 0b$$

$$5c + 0d \geq 4c + 1d$$

$$\Leftrightarrow b \geq a, \quad c \geq d$$

$$4a + 1c \geq 5a + 0c$$

$$5b + 0d \geq 4b + 1d$$

$$\Leftrightarrow c \geq a, \quad b \geq d$$

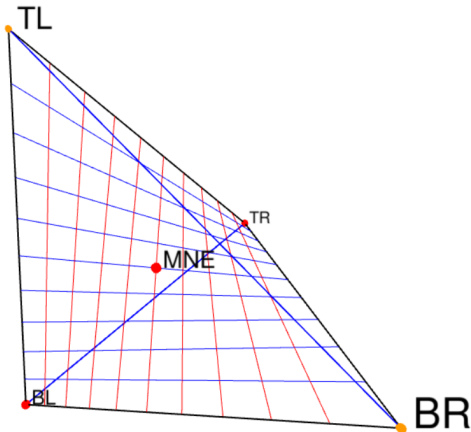
Linear incentive constraints!

set of correlated equilibria

- = **polytope**, defined by linear incentive constraints that compare any two strategies of a player
- **variables** = probabilities for strategy profiles
- holds for any number of players
- find easily CE with maximum payoff(-sum)

The correlated-equilibrium polytope

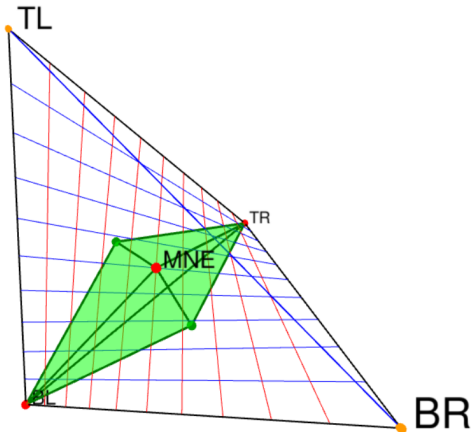
| | | | |
|---|----|---|--|
| | II | | |
| | L | R | |
| I | | | |
| T | 4 | 5 | |
| B | 1 | 0 | |
| | 5 | 0 | |



<http://www.maths.lse.ac.uk/Personal/stengel/05.html>

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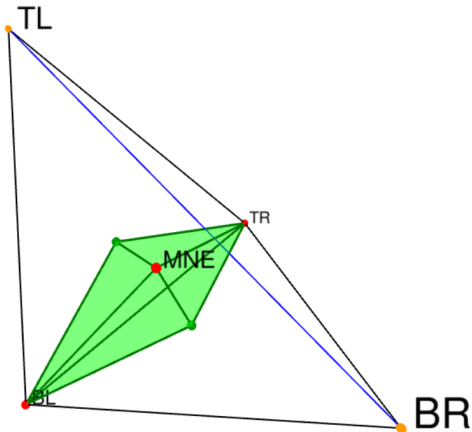
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The correlated-equilibrium polytope

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Existence proof

Correlated equilibrium and strategies

player i , pure strategy set \mathbf{S}_i , strategy profiles $\mathbf{S} = \mathbf{S}_i \times \mathbf{S}_{-i}$,
 $u^i(\mathbf{a}, \mathbf{s}_{-i}) = \text{payoff}$ to player i for $\mathbf{a} \in \mathbf{S}_i$.

Incentive constraints for CE distribution \mathbf{z} on \mathbf{S} :

for all players i and all $\mathbf{a}, \mathbf{b} \in \mathbf{S}_i$:

$$\sum_{\mathbf{s}_{-i} \in \mathbf{S}_{-i}} \mathbf{z}(\mathbf{a}, \mathbf{s}_{-i}) \left[u^i(\mathbf{a}, \mathbf{s}_{-i}) - u^i(\mathbf{b}, \mathbf{s}_{-i}) \right] \geq 0$$

LP existence proof for CE

[Hart/Schmeidler 1989; Nau/McCardle 1990]

Existence of CE via LP duality

Auxiliary game:

| | | |
|----------------------|--|---|
| Row | chooses $\mathbf{s} \in \mathbf{S}$ | mixes with $\mathbf{z}(\mathbf{s})$ |
| Col | chooses player i and $\mathbf{a}, \mathbf{b} \in \mathbf{S}_i$ | mixes with $\mathbf{y}_{\mathbf{a}\mathbf{b}}^i$ |
| payoff to Row | $= u^i(\mathbf{a}, \mathbf{s}_{-i}) - u^i(\mathbf{b}, \mathbf{s}_{-i})$ $= 0$ | if $\mathbf{s} = (\mathbf{a}, \mathbf{s}_{-i})$, otherwise. |

Payoff matrix \mathbf{U} , expected payoffs $\mathbf{z}^\top \mathbf{U} \mathbf{y}$.

Auxiliary game has value $0 \Leftrightarrow$ CE \mathbf{z} exists.

Expected payoff in auxiliary game

$$\mathbf{z}^\top \mathbf{U} \mathbf{y} =$$

$$\sum_i \sum_{\mathbf{s}_{-i} \in \mathbf{S}_{-i}} \sum_{\mathbf{a}, \mathbf{b} \in \mathbf{S}_i} \mathbf{z}(\mathbf{a}, \mathbf{s}_{-i}) \left[u^i(\mathbf{a}, \mathbf{s}_{-i}) - u^i(\mathbf{b}, \mathbf{s}_{-i}) \right] y_{\mathbf{a} \mathbf{b}}^i$$

to show value $\mathbf{0}$

it suffices: $\forall \mathbf{y} \exists$ pure \mathbf{s} : $(\mathbf{U} \mathbf{y})_{\mathbf{s}} \geq \mathbf{0}$

can show: $\forall \mathbf{y} \exists$ **product** distribution \mathbf{x} : $\mathbf{x}^\top \mathbf{U} \mathbf{y} = \mathbf{0}$

$$\mathbf{x}(\mathbf{s}) = \prod_i \mathbf{x}^i(\mathbf{s}_i).$$

Use product distribution

$$\begin{aligned} & \mathbf{x}^\top \mathbf{U} \mathbf{y} \\ &= \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} \sum_{a, b \in \mathcal{S}_i} x^i(a) x(\mathbf{s}_{-i}) \left[u^i(a, \mathbf{s}_{-i}) - u^i(b, \mathbf{s}_{-i}) \right] y_{ab}^i \\ &= \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} x(\mathbf{s}_{-i}) \cdot \square \end{aligned}$$

$$\square = \left[\sum_{a, b \in \mathcal{S}_i} x^i(a) u^i(a, \mathbf{s}_{-i}) y_{ab}^i - \sum_{a, b \in \mathcal{S}_i} x^i(a) u^i(b, \mathbf{s}_{-i}) y_{ab}^i \right]$$

Use product distribution

$$\begin{aligned} & \mathbf{x}^\top \mathbf{U} \mathbf{y} \\ = & \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} \sum_{a, b \in \mathcal{S}_i} x^i(a) x(\mathbf{s}_{-i}) \left[u^i(a, \mathbf{s}_{-i}) - u^i(b, \mathbf{s}_{-i}) \right] y_{ab}^i \\ = & \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} \mathbf{x}(\mathbf{s}_{-i}) \cdot \square \end{aligned}$$

$$\square = \left[\sum_{a, b \in \mathcal{S}_i} x^i(a) u^i(a, \mathbf{s}_{-i}) y_{ab}^i - \sum_{c, b \in \mathcal{S}_i} x^i(c) u^i(b, \mathbf{s}_{-i}) y_{cb}^i \right]$$

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Use product distribution

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$$\square = \sum_{a \in \mathcal{S}_i} u^i(\mathbf{a}, \mathbf{s}_{-i}) \left[x^i(\mathbf{a}) \sum_{b \in \mathcal{S}_i} y_{ab}^i - \sum_{c \in \mathcal{S}_i} x^i(\mathbf{c}) y_{ca}^i \right]$$

Use product distribution

$$\begin{aligned}
 & \mathbf{x}^\top \mathbf{U} \mathbf{y} \\
 = & \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} \sum_{\mathbf{a}, \mathbf{b} \in \mathcal{S}_i} \mathbf{x}^i(\mathbf{a}) \mathbf{x}(\mathbf{s}_{-i}) \left[u^i(\mathbf{a}, \mathbf{s}_{-i}) - u^i(\mathbf{b}, \mathbf{s}_{-i}) \right] \mathbf{y}_{\mathbf{a} \mathbf{b}}^i \\
 = & \sum_i \sum_{\mathbf{s}_{-i} \in \mathcal{S}_{-i}} \mathbf{x}(\mathbf{s}_{-i}) \cdot \square
 \end{aligned}$$

$$\square = \sum_{\mathbf{a} \in \mathcal{S}_i} u^i(\mathbf{a}, \mathbf{s}_{-i}) \left[\mathbf{x}^i(\mathbf{a}) \sum_{\mathbf{b} \in \mathcal{S}_i} \mathbf{y}_{\mathbf{a} \mathbf{b}}^i - \sum_{\mathbf{c} \in \mathcal{S}_i} \mathbf{x}^i(\mathbf{c}) \mathbf{y}_{\mathbf{c} \mathbf{a}}^i \right]$$

set \square to zero for suitable $\mathbf{x}^i(\mathbf{a})$ depending on $\mathbf{y}_{\mathbf{a} \mathbf{b}}^i$

Neutralizing deviation plans

Lemma [Hart/Schmeidler 1989]

(Lemma 12.10 in *Game Theory Basics*)

$\forall \mathbf{y}_{ab} \geq \mathbf{0} \exists$ probabilities $\mathbf{x}(\mathbf{a})$ [which give $\mathbf{x}^\top \mathbf{U} \mathbf{y} = \mathbf{0}$]

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Interpretation (for each original player i):

Increase w.l.o.g. diagonal elements \mathbf{y}_{aa} . Adversary's \mathbf{y} is a **Markov chain**, a “deviation plan” that says how to deviate from \mathbf{a} to \mathbf{b} .

Then \mathbf{x} is a **stationary distribution** that stays invariant under that Markov chain, so the adversary **gains nothing** with \mathbf{y} .

Neutralizing deviation plans

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(Lemma 12.10 in *Game Theory Basics*)

$\forall \mathbf{y}_{\mathbf{a}b} \geq \mathbf{0} \exists$ probabilities $\mathbf{x}(\mathbf{a})$ [which give $\mathbf{x}^\top \mathbf{U} \mathbf{y} = \mathbf{0}$]

$$\forall \mathbf{a} \in \mathbf{S}_i \quad \mathbf{x}(\mathbf{a}) \sum_{b \in \mathbf{S}_i} \mathbf{y}_{\mathbf{a}b} = \sum_{c \in \mathbf{S}_i} \mathbf{x}(\mathbf{c}) \mathbf{y}_{c\mathbf{a}}$$

Interpretation (for each original player i):

Increase w.l.o.g. diagonal elements $\mathbf{y}_{\mathbf{a}a}$. Adversary's \mathbf{y} is a **Markov chain**, a “deviation plan” that says how to deviate from \mathbf{a} to \mathbf{b} .

Then \mathbf{x} is a **stationary distribution** that stays invariant under that Markov chain, so the adversary **gains nothing** with \mathbf{y} .

\Rightarrow Auxiliary game has value $\mathbf{0}$, CE exists!

CE for compactly specified games

Example

Anonymous game with many players, same actions, and payoffs specified by **number** of other players choosing an action.

CE for compactly specified games

Example

Anonymous game with many players, same actions, and payoffs specified by **number** of other players choosing an action.

General compactly specified game = game in strategic form with

- polynomial number of players
- **polynomial number of actions per player**
- polynomial-time evaluation of payoffs for product profiles \mathbf{x}

⇒ **Theorem** [Papadimitriou/Roughgarden 2008]:
Can find **one** CE in polynomial time.

Algorithm [Papadimitriou/Roughgarden 2008]

- iterate **ellipsoid algorithm** to find deviation plans $\mathbf{y} = (\mathbf{y}_{a,b}^i)$
- in each iteration, neutralize via behavior profile \mathbf{x} to get $\mathbf{x}^\top \mathbf{U} \mathbf{y} = 0$
- derandomize \mathbf{x} to pure profile \mathbf{s} with payoff $(\mathbf{U} \mathbf{y})_{\mathbf{s}} \geq 0$ to **Row** [Jiang/Leyton-Brown 2010]
- infeasibility after polynomially many iterations

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 - derandomize \mathbf{x} to pure profile \mathbf{s} with payoff $(\mathbf{U} \mathbf{y})_{\mathbf{s}} \geq 0$ to **Row** [Jiang/Leyton-Brown 2010]
 - infeasibility after polynomially many iterations
- \Rightarrow polynomially many rows $\bar{\mathbf{U}}$ of \mathbf{U} suffice to solve $\bar{\mathbf{z}}^\top \bar{\mathbf{U}} \geq 0$
- \Rightarrow one CE $\bar{\mathbf{z}}$ found in polynomial time

Open problem

Given: Extensive game with perfect recall

Want: Find **one** CE for the strategic form in polynomial time.

Problem: Too many strategies to condition on!

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Alternative approach [von Stengel/Forges 2008]:

EFCE = Extensive-Form Correlated Equilibrium

recommending (and comparing / learning) **moves** rather than strategies.