

# Prophet Inequalities

## Part 2: Online matching and contention resolution

Paul Dütting, Google Research

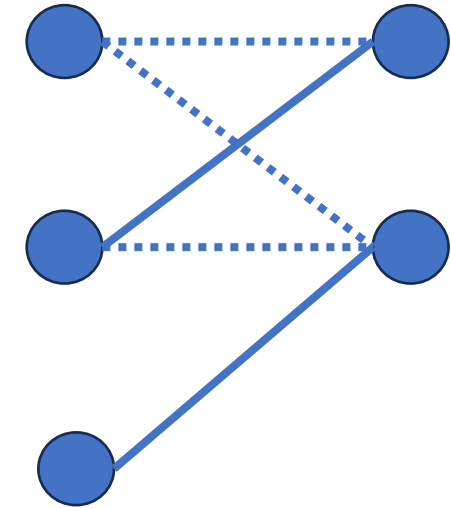
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# Online Matching

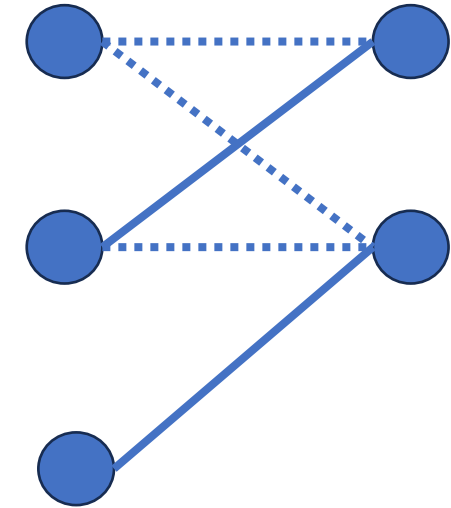
- Fundamental model with **numerous applications**:
  - Items and buyers (in e-commerce)
  - Drivers and passengers (in ridesharing platforms)
  - Ad slots and advertisers (in online ad auctions)
  - Jobs and workers (in online labor markets)
  - ...



Example: Matching in bipartite graph

# Online Matching

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  - Items and buyers (in e-commerce)
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  - ...
- Two flavors: **edge arrival** or **vertex arrival** (a.k.a. “batched arrival”)
- **Goal**: maximize total weight of chosen matching



Example: Matching in bipartite graph

# Plan for Part 2

- Alternative proof for single-choice prophet inequality
  - via: “online contention resolution”
- Prophet inequalities for online matching via this technique
  - with edge arrivals in general graphs
  - with vertex (“batched”) arrivals in general graphs

# High-Level Idea

- (Relax) Define a fractional relaxation
- (Round) Devise an online rounding scheme

# Outline Other Parts

**Part 1:** Introduction

**Part 2:** Online matching and contention resolution

**Part 3:** Online combinatorial auctions and balanced prices

**Part 4:** Data-driven prophet inequalities

# Additional References

Surveys and book chapters:

- “Online Matching: A Brief Survey” by Zhiyi Huang, Zhihao Gavin Tang, and David Wajc [[SIGEcom '24](#)]
- “Applications of Online Matching” by Zhiyi Huang and Thorben Tröbst (Chapter 5 in Echenique/Immorlica/Vazirani book) [[link](#)]
- “Online Matching in Advertisement Auctions” by Nikhil Devanur and Aranyak Mehta (Chapter 6 in Echenique/Immorlica/Vazirani book) [[link](#)]
- “Online Matching and Ad Allocation” by Aranyak Mehta (FnT-TCS Survey) [[link](#)]

# Additional References

Tutorials and workshops:

- FOCS 2023 Workshop “Online Algorithms and Online Rounding: Recent Progress” by Zhiyi Huang and David Wajc [[website](#)]
- WINE 2023 Tutorial “Recent Progress and Future Directions in Online Matching” by Zhiyi Huang and Zhihao Gavin Tang [[slides-pt1](#), [slides-pt2](#)]



Recall: The Classic Prophet Inequality

# The Problem

- Given known distributions  $\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_n$  over (non-negative) values:
  - A **gambler** gets to see realizations  $v_i \sim \mathcal{D}_i$  **one-by-one**, and needs to immediately and irrevocable decide whether to accept  $v_i$
  - The **prophet** sees the entire sequence of values  $v_1, v_2, \dots, v_n$  **at once**, and can simply choose the maximum value
- **Question:** What's the worst-case gap between  $\mathbb{E}[\text{value accepted by gambler}]$  and  $\mathbb{E}[\text{value accepted by prophet}]$ ?


$$= \mathbb{E}[\max_i v_i]$$


$$=: \mathbb{E}[ALG]$$

# Prophet Inequality

**Theorem** [Krengel-Succheston '77+'78] (+ Garling)

For all distributions  $\mathcal{D}_1, \mathcal{D}_2, \dots, \mathcal{D}_n$ , there is an algorithm ALG such that  $\mathbb{E}[ALG] \geq \frac{1}{2} \mathbb{E}[\max_i v_i]$ .



Krengel and Succheston in Oberwolfach

# A Different Proof: Online Contention Resolution Scheme (OCRS)

[Chekuri Vondrak Zenklusen '14, Feldman Svensson  
Zenklusen '16, Lee Singla '18]

# Proof via Contention Resolution

For simplicity suppose:  $v_i = x_i$  with probability  $p_i$ , and  $v_i = 0$  otherwise

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**Lemma:**  $\mathbb{E}[\max_i v_i]$  is at most:

**PROPHET**

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^n y_i \cdot x_i \\ & \text{subject to} && \sum_{i=1}^n y_i \leq 1 \quad \forall i \\ & && y_i \in [0, p_i] \quad \forall i \end{aligned}$$

**“ex ante relaxation”**

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“ex ante relaxation”

**Proof (of the lemma):**

Setting  $y_i = \Pr[x_i \text{ is chosen by prophet}]$  is feasible, and for this choice the objective value is equal to **PROPHET**.

**Q.E.D.**

# Proof via Contention Resolution

**Proof (of the prophet inequality):**

**ALG:** Upon arrival of element  $i$ , if  $v_i = x_i$ , then pick element  $i$  with prob.  $\frac{y_i}{2 \alpha_i p_i}$ ,  
where  $\alpha_i = 1 - \frac{1}{2} \sum_{j < i} y_j$  (= probability element  $i$  is reached)



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**Analysis:**

- $\frac{y_i}{2 \alpha_i p_i} \leq \frac{1}{2 \alpha_i} \leq 1$  where we used (1)  $y_i \leq p_i$  and (2)  $\alpha_i \geq 1 - \frac{1}{2} \sum_j y_j \geq \frac{1}{2}$

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- Every element  $i$  is picked w.p.  $y_i/2$ . Proof by induction:
  - Suppose this holds for every element  $j < i$
  - Then  $\Pr[i \text{ is picked}] = \Pr[i \text{ is reached}] \cdot \Pr[v_i = x_i] \cdot \frac{y_i}{2 \alpha_i p_i} = \alpha_i \cdot p_i \cdot \frac{y_i}{2 \alpha_i p_i} = \frac{y_i}{2}$

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- And so  $\mathbb{E}[\text{ALG}] = \sum_{i=1}^n \frac{y_i}{2} x_i \geq \frac{1}{2} \mathbb{E}[\max_i v_i]$  (by lemma)

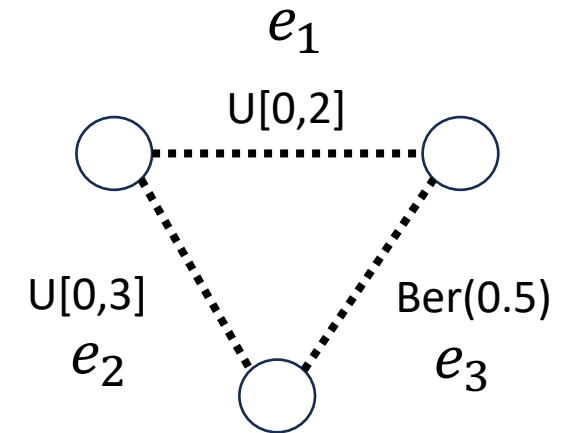
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# Online Matching with Edge Arrivals (in general graphs)

[Gravin Wang '19, Ezra Feldman Gravin Tang '20,  
MacRury Ma Grammel '23]

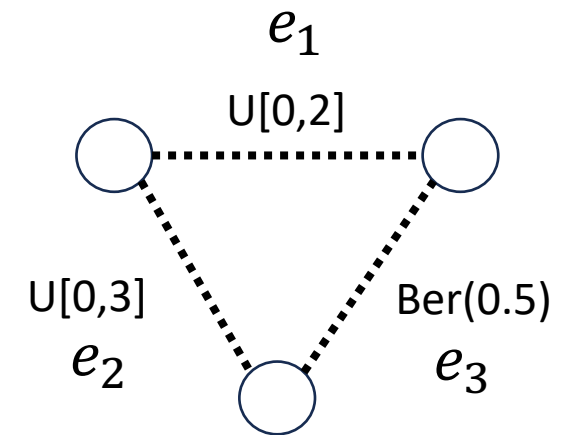
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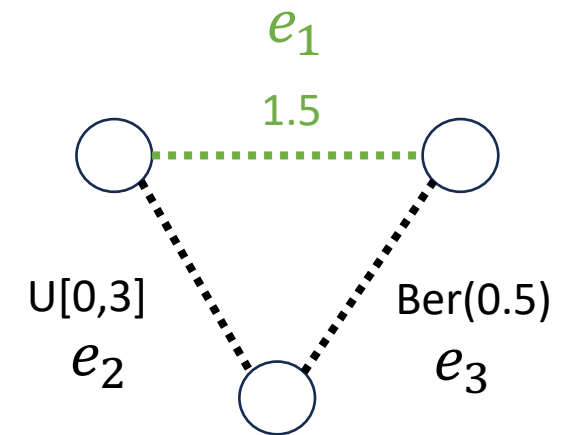
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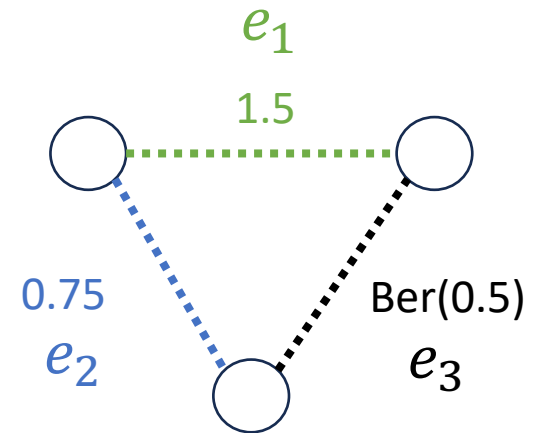
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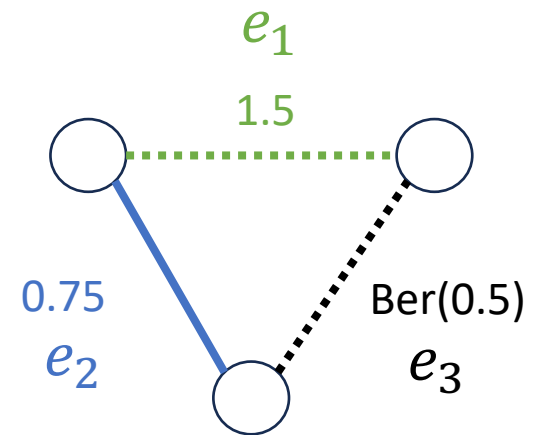
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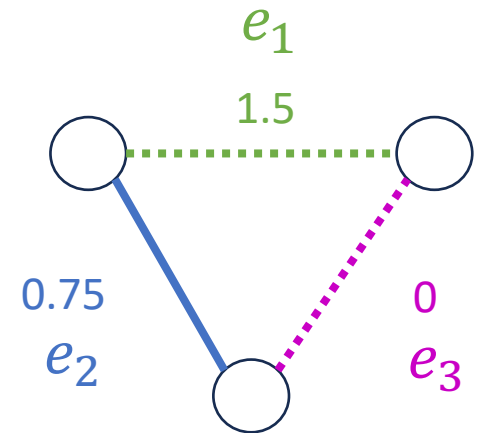
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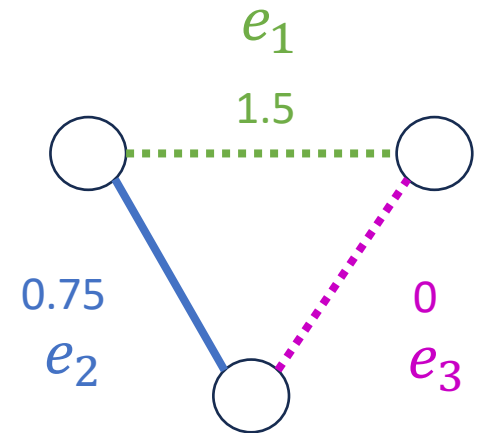
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ALG = 0.75  
OPT = 1.5

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**Theorem** [Ezra Feldman Gravin Tang '20]

There is an algorithm for online **matching** with **edge arrivals** in general graphs that is **3**-competitive against the prophet benchmark.

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State of the art:

	Lower bound	Upper bound
Bipartite graphs	$\geq 2.25$ [Gravin and Wang '19] $\geq 7/3$ [Correa Cristi Fielbaum Pollner Weinberg '22]	$\leq 3$ [Gravin Tang '19] $\leq 2.865$ [MacRury Ma Grammel '23]
General graphs	$\geq 2.5$ [MacRury, Ma, Grammel '23] $\geq 2.564$ for OCRS-based approaches	$\leq 2.967$ [Ezra Feldman Gravin Tang '20] $\leq 2.907$ [MacRury Ma Grammel '23]

# OCRS Proof

For simplicity suppose:  $w_e = x_e$  with probability  $p_e$ , and  $w_e = 0$  otherwise

**Lemma:**  $\mathbb{E} \left[ \underbrace{\max_M w(M)}_{\text{PROPHET}} \right]$  is at most:

$$\begin{aligned} \max \quad & \sum_e y_e \cdot x_e \\ \text{s.t.} \quad & \sum_{e:u \in e} y_e \leq 1 \quad \forall \text{ node } u \\ & y_e \in [0, p_e] \quad \forall \text{ edge } e \end{aligned}$$

“ex ante relaxation”  
(cf. fractional matching polytope)

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**Proof (of the prophet inequality):**

**ALG:** Upon arrival of edge  $e = (u, v)$ , if  $w_e = x_e$  and  $e$  is available (i.e.,  $u$  and  $v$  are available), then match edge  $e$  with prob.  $\frac{y_e}{3 \alpha_e p_e}$ , where  $\alpha_e = \Pr[e \text{ available}]$

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- $\frac{y_e}{3 \alpha_e p_e} \leq \frac{1}{3 \alpha_e} \leq 1$  because (1)  $y_e \leq p_e$  and (2)  $\alpha_e \geq 1 - \Pr[u \text{ unavailable}] - \Pr[v \text{ unavailable}] \geq \frac{1}{3}$  (by union bound)
  - $\Pr[u \text{ unavailable}] = \sum_{e' < e: u \in e'} \Pr[e' \text{ matched}] = \sum_{e' < e: u \in e'} \frac{y_{e'}}{3} \leq \frac{1}{3}$

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- And so  $\mathbb{E}[\text{ALG}] = \sum_e \frac{y_e}{3} x_e \geq \frac{1}{3} \mathbb{E} \left[ \max_M w(M) \right]$  (by lemma)

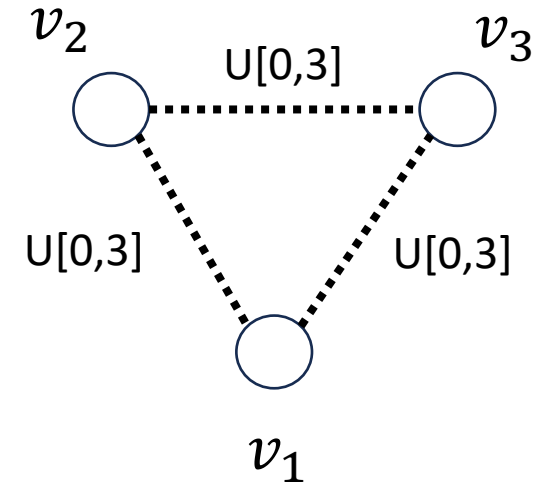
**Q.E.D.**

# Online Matching with Vertex Arrivals (in general graphs)

[Ezra Feldman Gravin Tang '20]

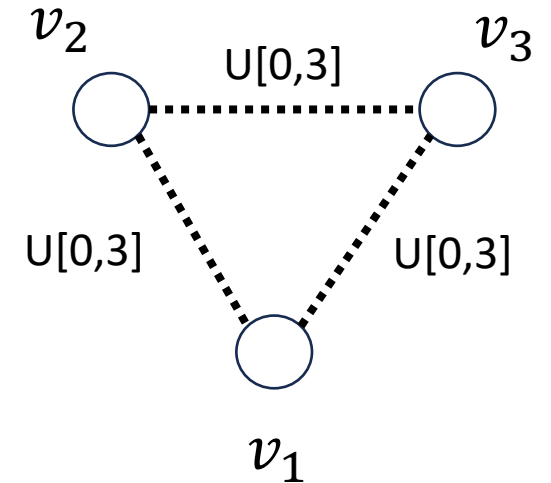
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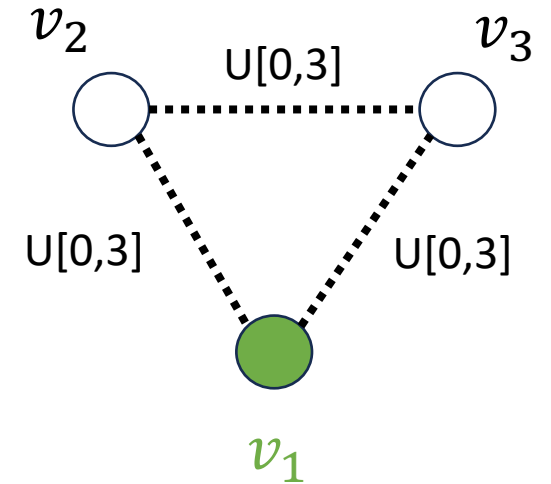
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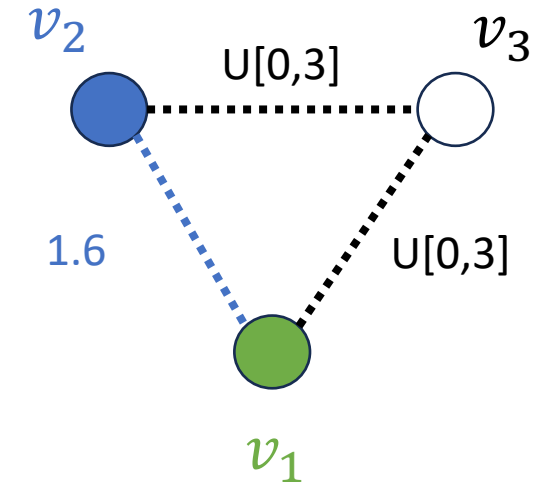
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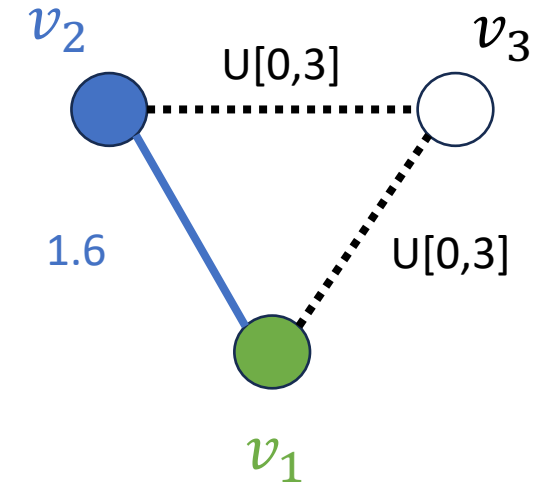
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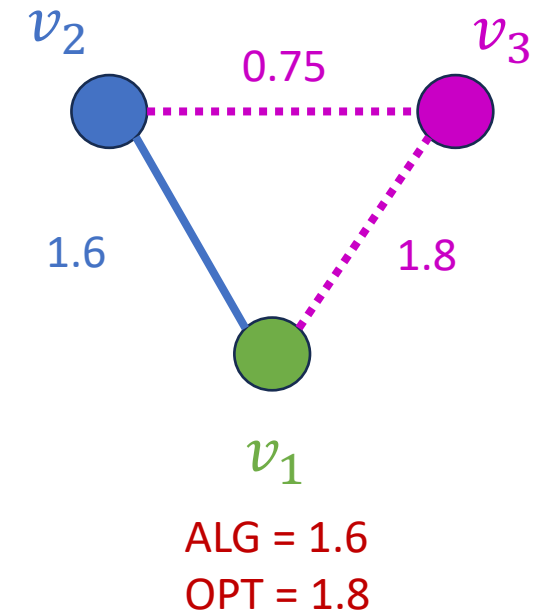
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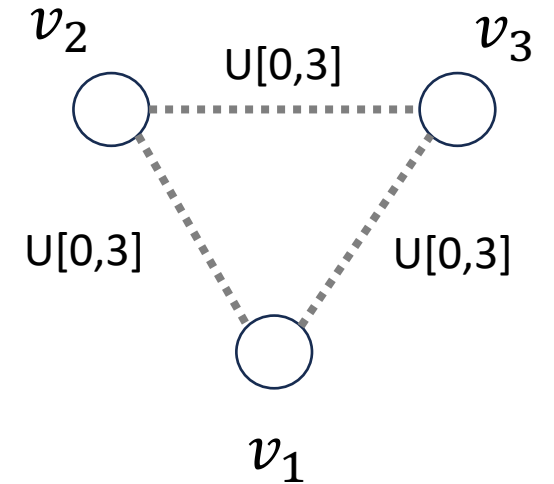
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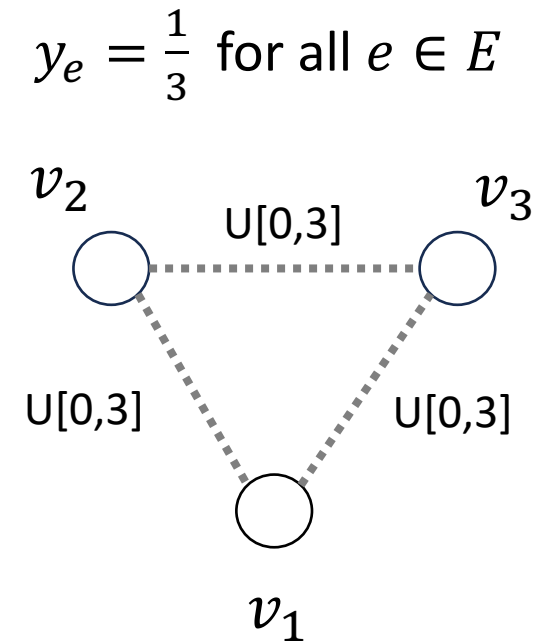
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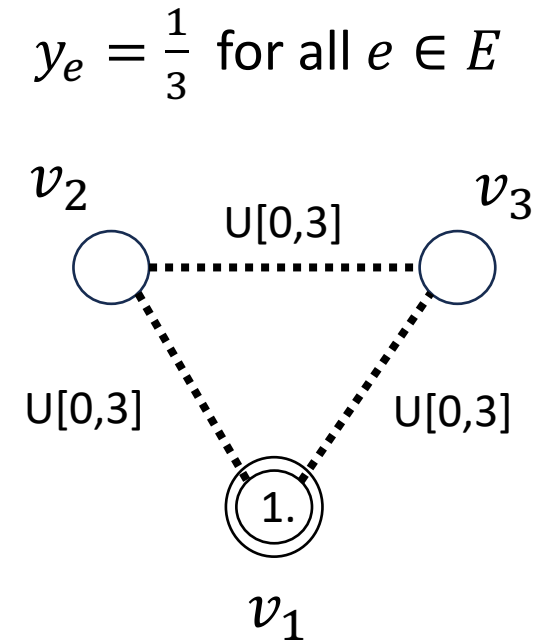
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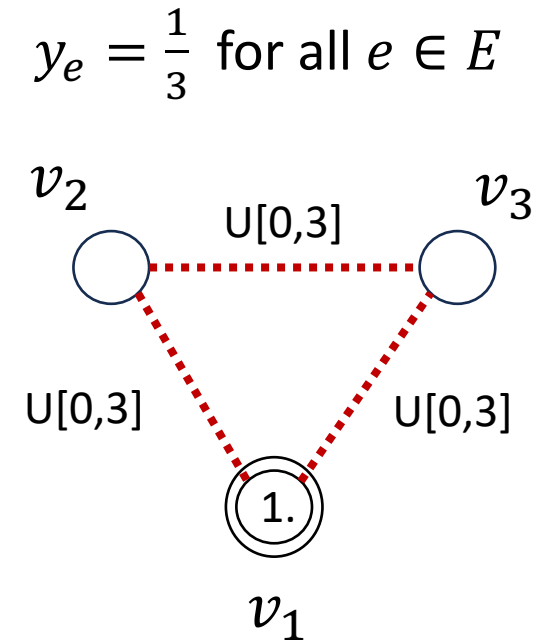
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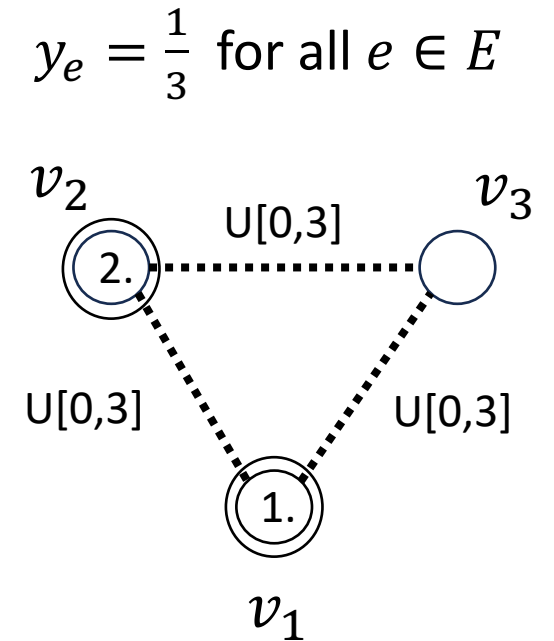
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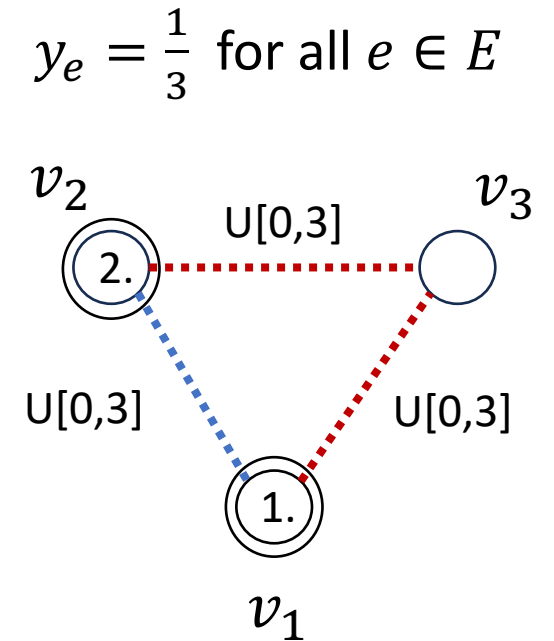
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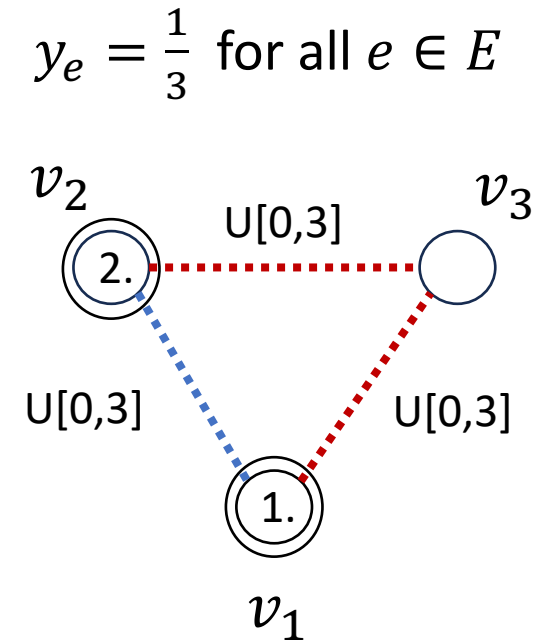
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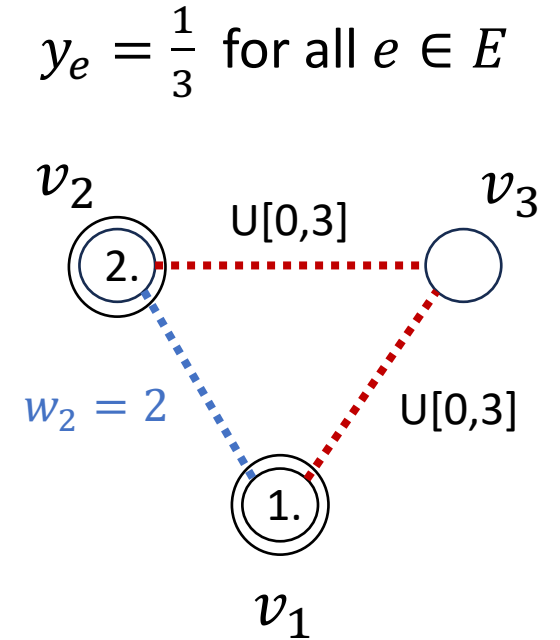
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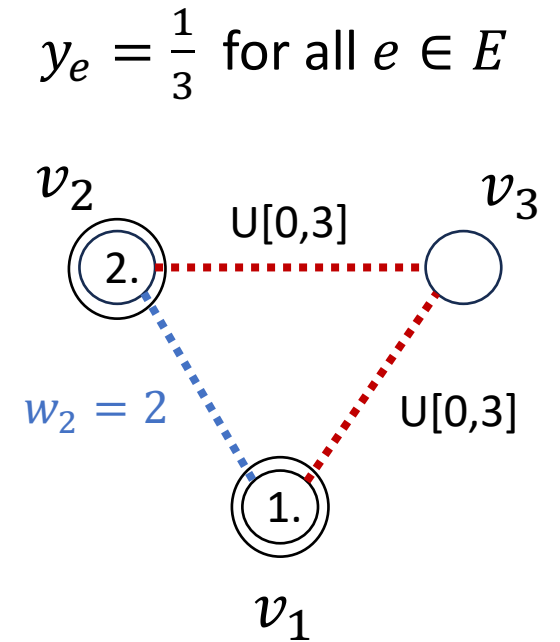
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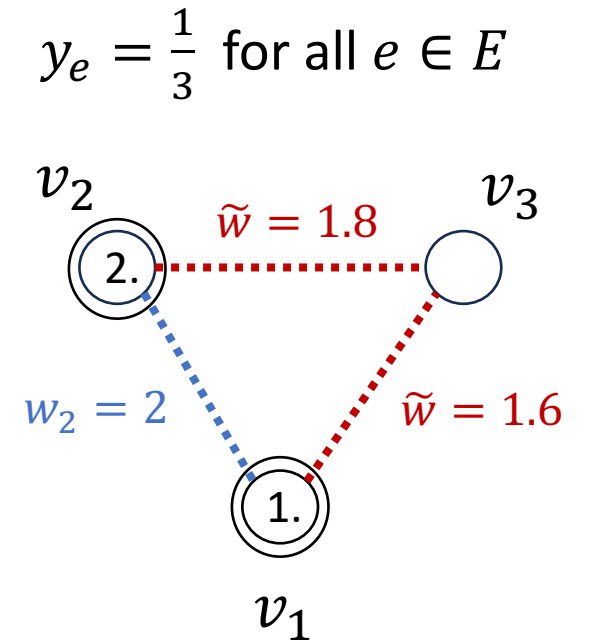
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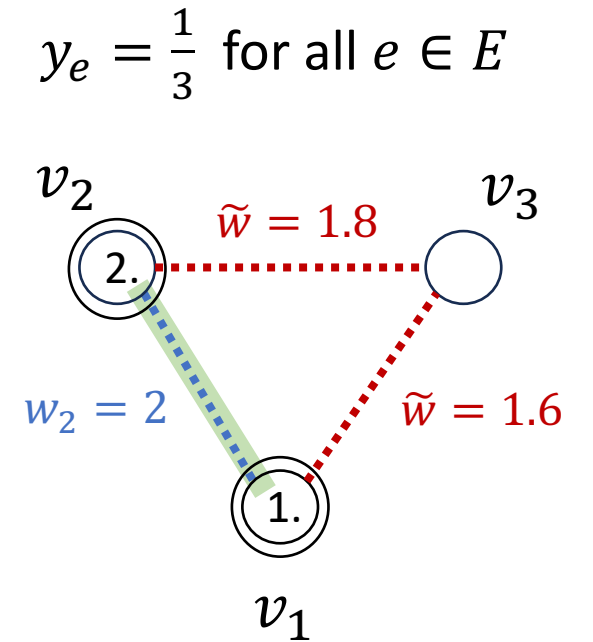
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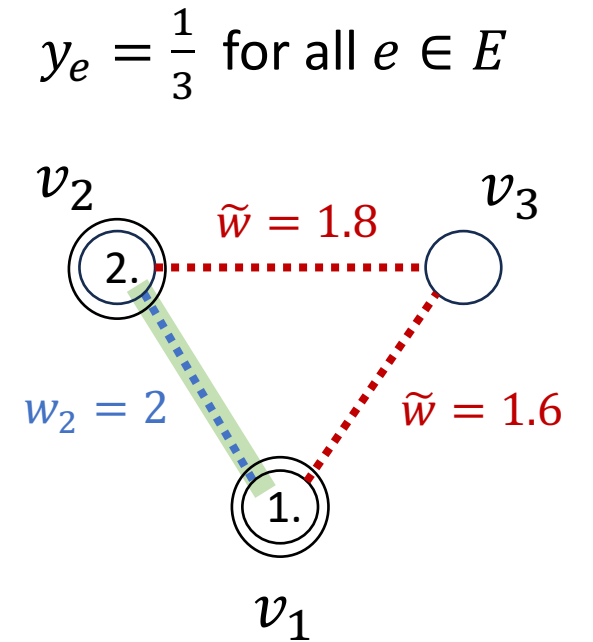
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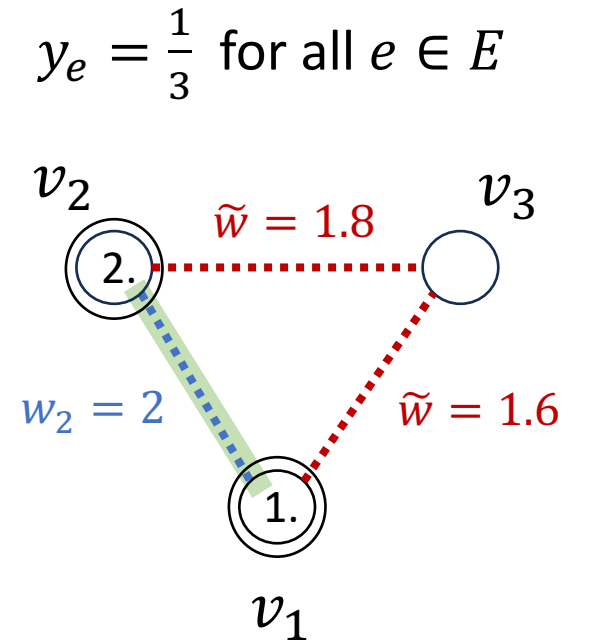
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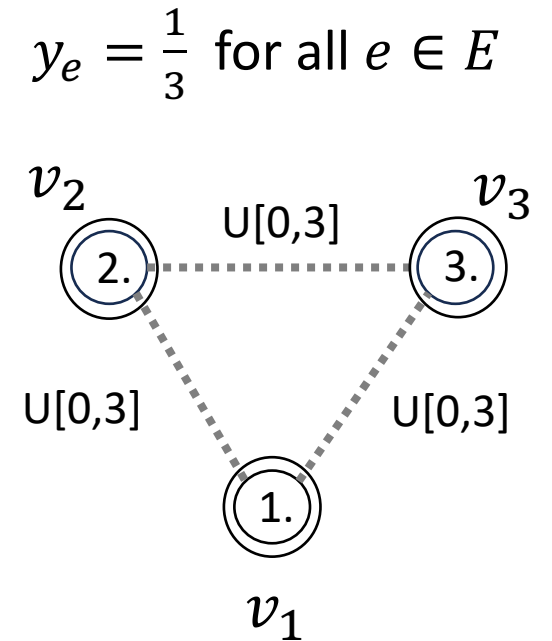


Match  $(2, 1)$  with prob.

$$\frac{1}{2 - \sum_{r < 2} y_{(r,1)}} = \frac{1}{2}$$

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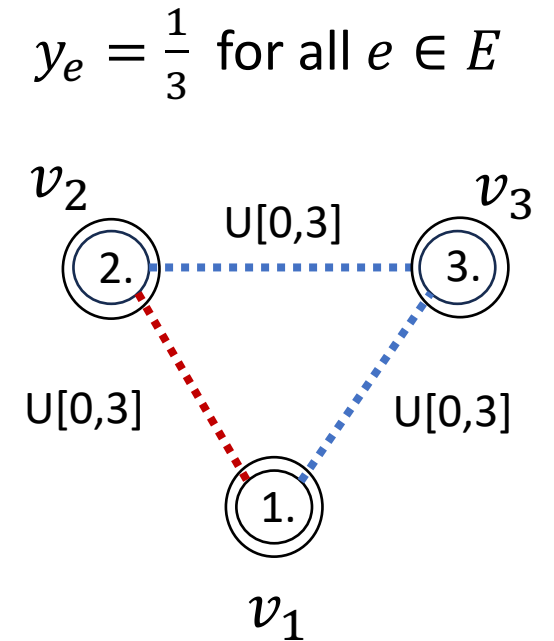
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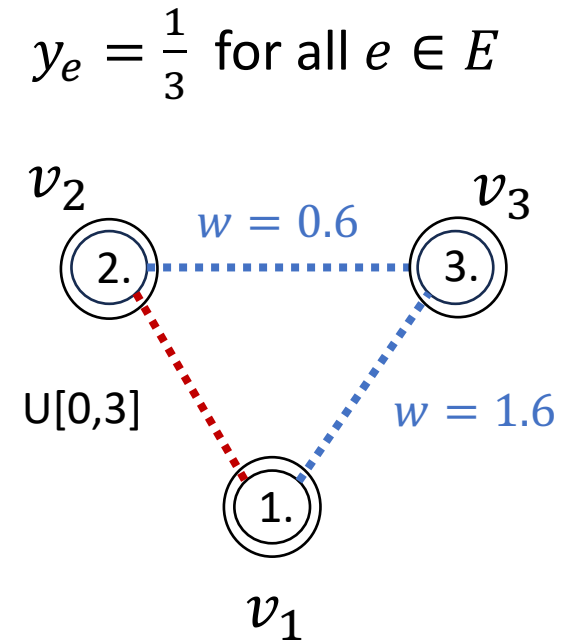
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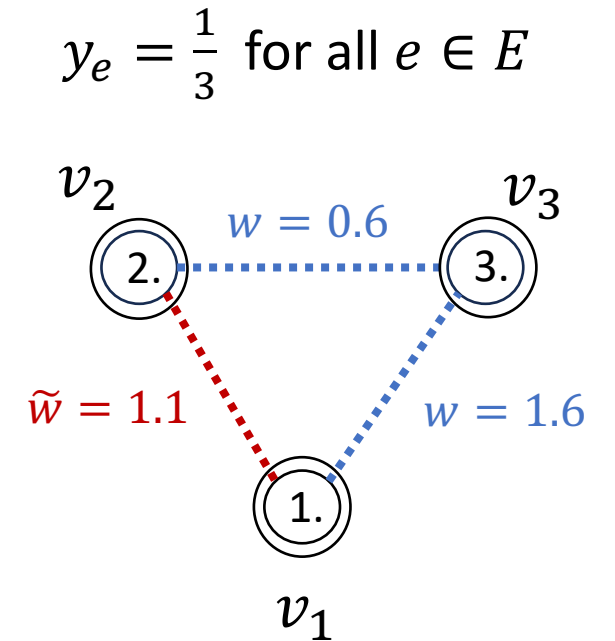
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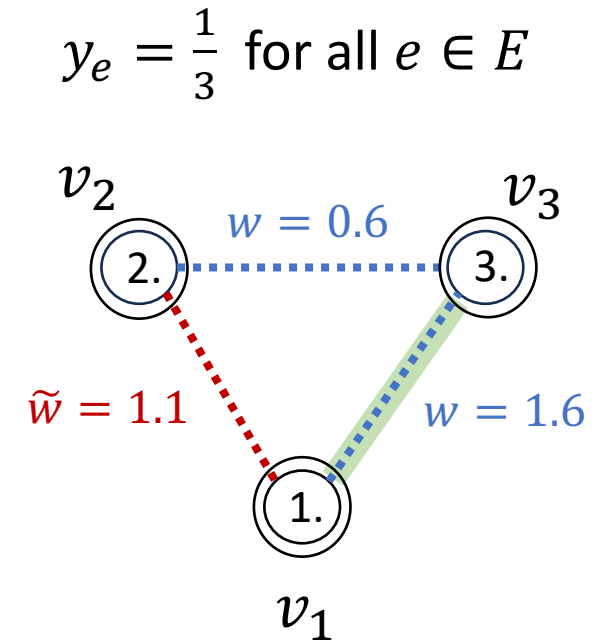
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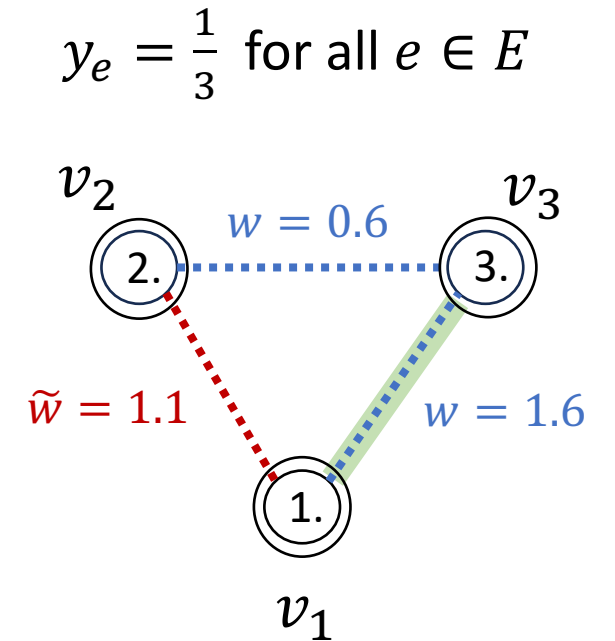
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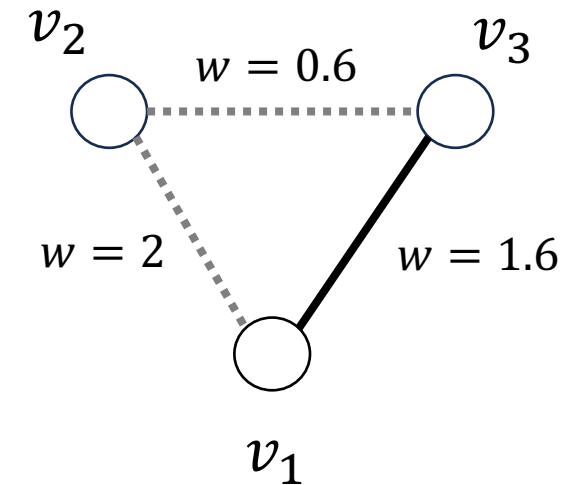


Match (3, 1) with prob.

$$\frac{1}{2 - \sum_{r < 3} y_{(r,1)}} = \frac{3}{5}$$

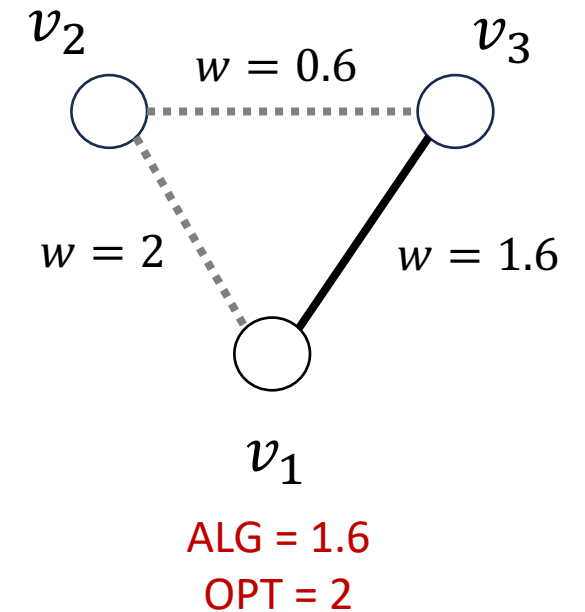
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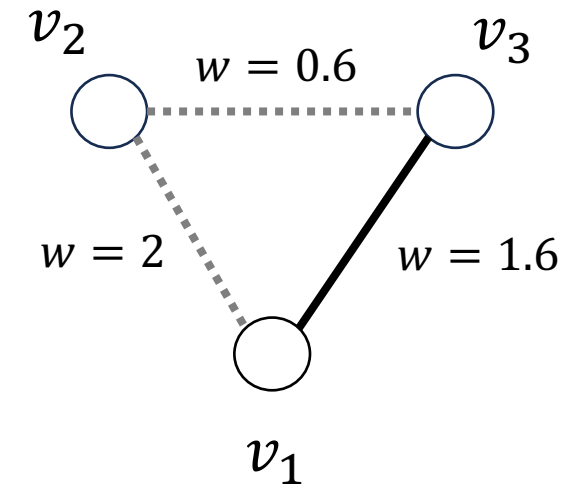


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**Note:**  $\alpha_u(v) \leq 1$  because  $\sum_{r < v} y_{(r,u)} \leq 1$



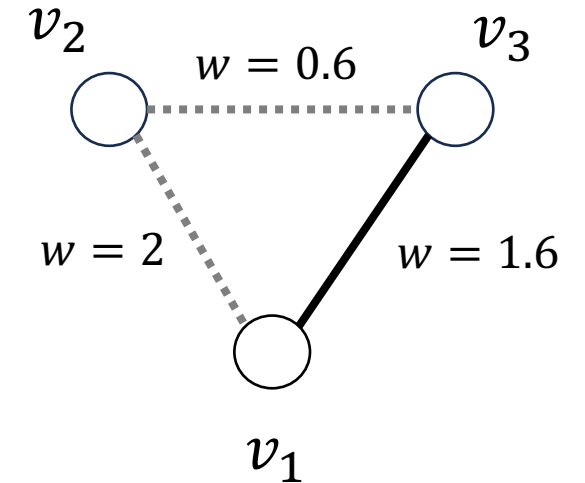
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“provisional edges”



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**Proof:** By induction:

$$\underbrace{\left(1 - \frac{\sum_{r < v} y(r, u)}{2}\right)}_{u \text{ is available}} \cdot \underbrace{\left(\frac{1}{2 - \sum_{r < v} y(r, u)}\right)}_{\alpha_u(v)} = \frac{1}{2}$$

**Q.E.D.**

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**Conclusion:** ALG has a competitive ratio of  $1/2$ .

**Q.E.D.**

# Additional Directions

- Better understanding of **random-order OCRS** for matching and other problems. Recent progress in [MacRury Ma 2024], but not yet fully understood.
- Infinite-time horizon prophet inequalities (cf. the Stationary Prophet Inequality Problem). Has connections to **(offline) contention resolution schemes (CRS)** [Kessel Sharnali Patel Saberi Wajc '22, Patel Wajc '24]
- **Online correlated selection (OCS)** as in [Fahrback, Huang, Tao, and Zadimoghaddam '20] (and follow-up). Has some connection to OCRS. Making this connection tighter and more explicit is an interesting direction.
- **Online dependent rounding**. One can do better than offline single-item CRS (1.519), but no better than  $1/(2\sqrt{2} - 2) \approx 1.208$ . What's the right answer? Known techniques relate to philosopher inequality, and online edge coloring multi-graphs. [Naor Srinivasan Wajc 23+]

# Summary

- Alternative proof for single-choice prophet inequality
  - via: “online contention resolution”
- Prophet inequalities for online matching via this technique
  - with edge arrivals in general graphs
  - with vertex (“batched”) arrivals in general graphs

Thanks! Coffee!