Graph Algorithms

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1. Open Problem (€100)

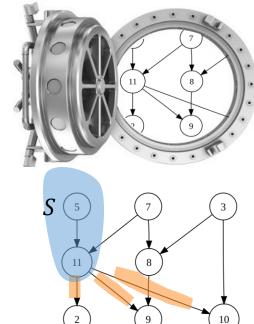
Open: Cut Query for Reachability

V = # nodes, E = # edges, \tilde{O} hides polylog(V)

- Input: Hidden unweighted directed graph G=(V, E)
- Query access: For $S \subseteq V$, cut(S) = # edges going out from S
- Return: Exist path from nodes s to t?



Exercise 2: $\tilde{O}(V^2)$ even for more general problems [Cunningham'83]



 $cut({5,11})=3$

Open: $\tilde{O}(V^{1.99})$

Ultimate: $\tilde{O}(V)$ & more

Solution. Observe: [Mehra-Mukhopadhyay'24]

1. $\operatorname{cut}(S) + \operatorname{cut}(V \setminus S) = \sum_{u \in S, v \in V \setminus S} w(uv) + w(vu)$ where w(uv) is the "weight" of edge from u to v.

2. $\operatorname{cut}(S) - \operatorname{cut}(V \setminus S) = \sum_{u \in S} \operatorname{outdegree}(u) - \operatorname{indegree}(u)$

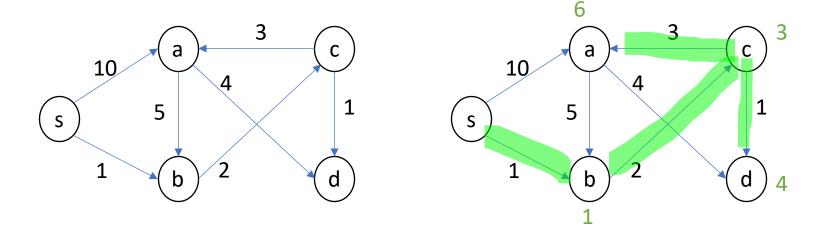
Thus: compute all possible w(uv), outdegree(u) and indegree(u)

Why? Submodular Function Minimization (SFM)

- Recall: For sets $X \subseteq Y$ and $x \notin Y$, $f(X \cup \{u\}) f(X) \ge f(Y \cup \{u\}) f(Y)$
- <u>Special cases</u>: Reachability, Min-cut/Max-flow, Matching, Matroid intersection, Disjoint trees, ...
- Known for SFM: $\tilde{O}(n^2)$ & $\Omega(n \log n)$ value queries.
 - Grötschel, Lovász and Schrijver 1984 & 1988; Lee, Sidford and Wong 2015; Jiang 2021; Chakrabarty, Graur, Jiang, and Sidford 2022
- Open: $O(n^{1.99})$ and $\Omega(n^{1.01})$
 - We can't even solve reachability in $O(n^{1.99})$ queries

2. Shortest Paths

Single-Source Shortest Paths



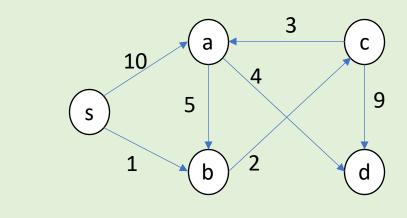
- Input: Directed weighted graph G = (V, E, w), source $s \in V$
- Output: Minimum-cost path from s to every $v \in V$



Textbook algorithms

Dijkstra

- + Near-optimal time $(O(E + V \log V) \text{ time})$
- Only **non**negative weights.



But sometimes we need both positive and negative weights:



Ships/airplanes routing



Arbitrage trading

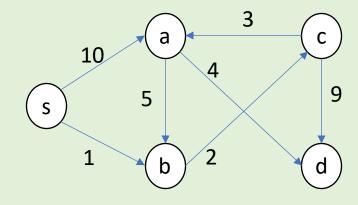
Also job scheduling, periodic optimization, control theory,

...

Textbook algorithms

Dijkstra

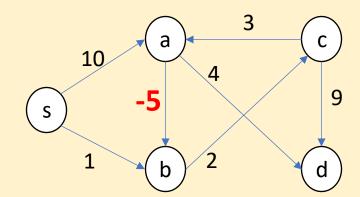
- + Near-optimal time $(O(E + V \log V) \text{ time})$
- Only **non**negative weights.



Near linear = $E log^{O(1)} E$ e.g. $E log^{10} E$

Bellman-Ford

- + Allow negative weights
- Far from near-linear time (O(VE) time)

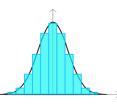


Research question: Near-linear time algorithm for negative-weight SSSP?



Textbook (from 1950s): O(EV) [Shimbel'55, Ford'56, Bellman'58, Moore'59]

Assume **integer** weights -W, -W+1, -W+2..., 0, 1, 2, ...



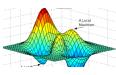
1980s-1990s Approximation/scaling techniques: $O(E\sqrt{V}\log W)^2$

Gabow'85 ($EV^{\frac{3}{4}}\log V$), Gabow-Tarjan'89 ($EV^{\frac{1}{2}}\log(VW)$), Goldberg'95 ($EV^{\frac{1}{2}}\log(W)$)



2000s Special graphs:

 $\tilde{O}(E)$ time for planar graphs [Fakcharoenphol-Rao'06, Mozes-Wulff-Nilsen'10] $\tilde{O}(V^{4/3}\log W)$ time for bounded-genus & minor-free graphs [Wulff-Nilsen'11]



2010+: Continuous Methods + Dynamic Graphs: $E^{\frac{4}{3}+o(1)} \log W$, $\tilde{O}(E+V^{1.5} \log W)$



Cohen, Madry, Sankowski, Vladu'17 ($(E^{10/7+o(1)}\log W)$, Axiotis, Madry, Vlady, 2020 ($E^{4/3+o(1)}\log W$), van den Brand, Lee, N, Peng, Saranurak, Sidford, Song, Wang 2020 ($E+V^{1.5}\log W$)

Our results: Near-linear time shortest path

(2022) $O(E \log^8 V \log(W))$ time in expectation Bernstein, N., Wulff-Nilsen

(2023) $O(E \log^2 V \log(VW) \log \log V)$ time in expectation Bringmann, Cassis, Fischer

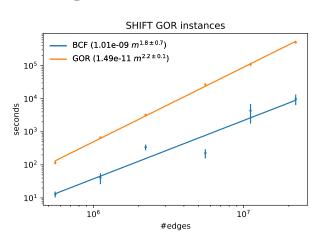
(2024) Efficient in Parallel, Distributed, and Quantum Settings

Ashvinkumar, Bernstein, Cao, Grunau, Haeupler, Jiang, N., Su

(2024) Experimental results

Bringmann, Cassis, Karrenbauer, Nusser, Rinaldi

Codable. Teachable. Efficient in many settings.



Key Techniques: Low-Diameter Decomposition (LDD)

Definition of LDD(G,D)

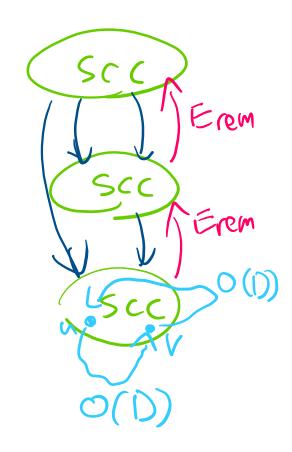
(Oversimplified)

Input: Directed graph G = (V, E) & positive integer D

Output: $E_{Rem} \subseteq E$ such that

- 1. each **SCCs** of $G \setminus E_{rem}$ has diameter O(D)
 - i.e. for u, v in the same SCC, distance(u, v) = O(D) & distance(v, u) = O(D)
- 2. $\forall e \in E, \Pr[e \in E_{rem}] = O\left(\frac{1}{D}\right)$.

Runtime: $\tilde{O}(E)$ in expectation.



Example (1)

 $G = \text{undirected path } (v_1, v_2, \dots, v_n)$

Getting LDD(G, D):

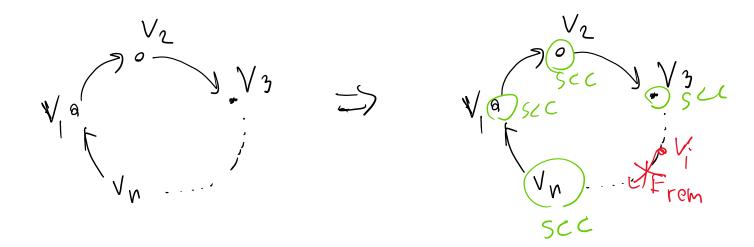
- randomly select $i \in [1, D]$
- add edges (v_i, v_{i+1}) , (v_{i+D}, v_{i+D+1}) , (v_{i+2D}, v_{i+2D+1}) , ... to E_{rem}

Example (2)

 $G = \text{directed cycle } (v_1, v_2, \dots, v_n)$

Getting LDD(G, D): randomly add one edge to E_{rem}

→ Each node becomes an SCC



How to use LDD? - Solve this first (€1)

Solve this problem in near-linear time:

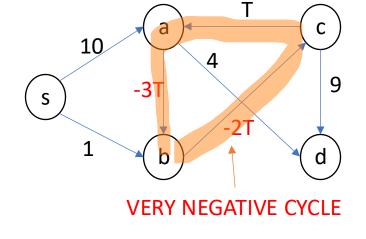
Input: Strongly-connected directed graph G = (V, E) with integer edge weight w for some integer T > 0.

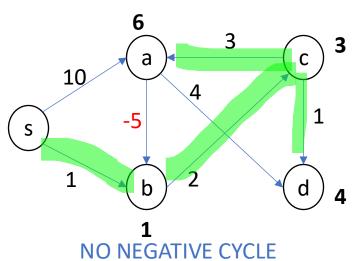
Promise: The diameter of G is at most 10T; i.e. for every vertices u and v, there is a path from u to v with weight at most 10T.

Output: Either report a cycle whose average edge weight is <-T or report that no negative cycle exists:

- Output "VERY NEGATIVE CYCLE" if there is a cycle (sequence of vertices) $v_1, v_2, \ldots, v_k = v_1$, such that $\sum_{i=1}^{k-1} w(v_i, v_{i+1}) < -T$.
- Output "NO NEGATIVE CYCLE" if there is for every cycle $v_1, v_2, \ldots, v_k = v_1$, $\sum_{i=1}^{k-1} w(v_i, v_{i+1}) \ge 0$.

For other cases, you can output any of the above.





Solution to this problem and LDD are two key ideas